

# Two Logarithmic Approximation Algorithms for Multicut<sup>1</sup>

- In this lecture we consider the multicut problem which generalizes the multiway cut problem. As usual, we are given an undirected graph  $G = (V, E)$  with non-negative costs  $c(e)$  on edges. We are also given  $k$  pairs of vertices  $\{s_i, t_i\}_{i=1, \dots, k}$ . The objective is to find a subset  $F \subseteq E$  of minimum cost such that in  $G \setminus F$ ,  $s_i$  is disconnected from  $t_i$ . Note that  $s_i$  could remain connected to  $t_j$ . We describe two  $O(\log k)$ -approximation algorithms for this problem. They are both based on the same distance-based LP relaxation.

$$\text{lp} := \min \sum_{e \in E} c(e)x_e \quad (\text{Multicut LP})$$

$$d_{uv} \leq x_e, \quad \forall e \in E, e = (u, v) \quad (1)$$

$$d_{uw} \leq d_{uv} + d_{vw}, \quad \forall i \in F, \forall \{u, v, w\} \subseteq V \quad (2)$$

$$d_{vv} = 0, \quad \forall v \in V \quad (3)$$

$$d_{s_i t_i} \geq 1, \quad \forall 1 \leq i \leq k \quad (4)$$

- Randomized Rounding Algorithm.** The first rounding algorithm we see is a generalization of the multiway cut algorithm. We select a random radius  $r \in (0, 0.5)$  uniformly at random. Then, we wish to go over each terminal  $s_i$  and “carve out” the region of radius  $r$  around  $S_i$ . The twist in this algorithm is this: go over the terminals also randomly.

- 1: **procedure** RANDOMIZED MULTICUT( $G = (V, E)$ ,  $c(e) \geq 0$  on edges,  $\{s_i, t_i\}_{i=1, \dots, k}$ ):
- 2:   Solve (Multicut LP) to obtain  $x_e$ 's and  $d_{uv}$ 's.
- 3:   Randomly sample  $r \in (0, 0.5)$  uniformly.
- 4:   Randomly sample  $\sigma$ , a permutation of  $\{1, \dots, k\}$ .
- 5:   Let  $S_i := \{v : d_{s_i v} \leq r\}$  and let  $E[S_i] := \{(u, v) : u, v \in S_i\}$ .
- 6:   For  $1 \leq i \leq k$ : add  $\partial S_{\sigma(i)} \setminus \bigcup_{j < i} E[S_{\sigma(j)}]$  to  $F$ .
- 7:   **return**  $F$ .

- Analysis.* First let us observe  $F$  is a valid multicut.

**Claim 1.**  $F$  separates all  $s_i, t_i$  pairs.

*Proof.* By design, observe that for any  $i$ , the subset  $S_i$  doesn't contain both  $s_j$  and  $t_j$  for any  $j$ . Now, note that since  $\partial S_{\sigma(i)} \setminus \bigcup_{j < i} E[S_{\sigma(j)}]$  is added to  $F$ , in  $G \setminus F$  the vertex  $s_{\sigma(i)}$  is disconnected from all vertices outside  $S_{\sigma(i)}$ , except maybe those in  $S_{\sigma(j)} : j < i$  which contained the vertex  $s_{\sigma(i)}$ . By the observation above, such  $S_{\sigma(j)}$ 's don't contain  $t_{\sigma(i)}$ . Therefore,  $s_{\sigma(i)}$  is disconnected from  $t_{\sigma(i)}$ .  $\square$

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These have not gone through scrutiny and may contain errors. If you find any, or have any other comments, please email me at deeparnab@dartmouth.edu. Highly appreciated!

**Theorem 1.** The expected cost of the edges  $F$  returned by RANDOMIZED MULTICUT is  $\leq 2H_k \text{lp}$  where  $H_k$  is the  $k$ th Harmonic number.

*Proof.* Fix an edge  $(u, v)$ . The proof of the theorem follows if we prove  $\Pr[(u, v) \in F] \leq 2H_k \cdot d_{uv}$ . Note that the probability is now both over our choice of  $r$  and the random permutation of the terminals.

Define  $\mathcal{E}_i(u, v)$  to be the event that *exactly* one of  $u$  or  $v$  lies in  $S_i$ . That is,  $\min(d_{s_i u}, d_{s_i v}) \leq r < \max(d_{s_i u}, d_{s_i v})$ . Define  $\mathcal{E}'_i(u, v)$  to be the event that *both*  $u$  and  $v$  lie in  $S_i$ , that is  $r < \min(d_{s_i u}, d_{s_i v})$ . Now, note that the edge  $(u, v)$  appears in the solution  $F$  if and only if there is some  $i$  such that  $\mathcal{E}_i$  occurs **and** for all  $j < i$ ,  $\mathcal{E}'_j$  **doesn't** occur. That is,

$$\Pr[(u, v) \in F] = \Pr_{\sigma, r} \left[ \exists i : \mathcal{E}_{\sigma(i)}(u, v) \text{ and } \bigwedge_{j < i} \mathcal{E}'_{\sigma(j)}(u, v) \right] \quad (5)$$

Fix an  $i$  between 1 and  $k$ . Without loss of generality, assume  $d_{s_{\sigma(i)} u} \leq d_{s_{\sigma(i)} v}$ . Note that  $\bigwedge_{j < i} \mathcal{E}'_{\sigma(j)}(u, v)$  occurs only if  $r < d_{s_{\sigma(j)} v}$  for all  $j < i$ . But  $\mathcal{E}_{\sigma(i)}(u, v)$  occurs only if  $r \geq d(s_{\sigma(i)}, u)$ . So, we can upper bound the probability in the RHS above as

$$\Pr_{\sigma, r} \left[ \mathcal{E}_{\sigma(i)}(u, v) \text{ and } \bigwedge_{j < i} \mathcal{E}'_{\sigma(j)}(u, v) \right] \leq \Pr_{\sigma, r} \left[ r \in [d_{s_{\sigma(i)} u}, d_{s_{\sigma(i)} v}] \text{ and } \bigwedge_{j < i} \left\{ d_{s_{\sigma(i)} u} < d_{s_{\sigma(j)} u} \right\} \right]$$

Note that the two events in the RHS above are independent: the first depends only on  $r$ , the second depends only on  $\sigma$ , and they were chosen independently. So, by union bound we get that the RHS of (5) is at most

$$\sum_{i=1}^k \underbrace{\Pr_r \left[ r \in [d_{s_{\sigma(i)} u}, d_{s_{\sigma(i)} v}] \right]}_{\text{call this } \pi_1(i)} \cdot \underbrace{\Pr_{\sigma} \left[ \bigwedge_{j < i} \left\{ d_{s_{\sigma(i)} u} < d_{s_{\sigma(j)} u} \right\} \right]}_{\text{call this } \pi_2(i)}$$

We know  $\pi_1(i) = \Pr_r \left[ r \in [d_{s_{\sigma(i)} u}, d_{s_{\sigma(i)} v}] \right] \leq 2d_{uv} \leq 2x_e$ . This is similar to the mincut argument;  $r$  is chosen randomly from an interval of length 0.5 and the length of  $[d_{s_{\sigma(i)} u}, d_{s_{\sigma(i)} v}]$ , by (2) is at most  $d_{uv} \leq x_e$ .

To evaluate  $\pi_2(i)$ , consider the  $k$  distances  $d_{s_i u}$  from  $u$  to each  $s_i$ . What  $\pi_2$  is asking is to figure out the probability that in a random permutation of these  $k$  distances, the  $i$ th distance is the minimum among the first  $i$ . This is precisely  $1/i$ . Therefore, the probability in the RHS of (5) is at most  $\sum_{i=1}^k \frac{2x_e}{i} = 2H_k \cdot x_e$ . This completes the proof.  $\square$

- **A Region Growing Algorithm.** We now describe another algorithm for the multicut problem. This algorithm uses a technique called *region growing* which will be useful for the next cut-problem we look at. It also has applications in other related problems.

We start with a couple of definitions. Let's fix a solution to (Multicut LP), and a parameter  $r \in [0, 0.5)$ . For a subset  $U \subseteq V$ , define  $S_i(r; U) := \{u \in U : d_{s_i u} \leq r\}$ . Define  $\partial S_i(r; U) := \{(u, v) \in E :$

$u \in S_i(r; U), v \in U \setminus S_i(r)$ , and define  $E[S_i(r; U)] = \{(u, v) \in E : u, v \in S_i(r; U)\}$ . These definitions are similar to the ones used above, except we pass on an extra parameter  $U$ .

Next, define the “volume” of a ball of radius  $r$  around the center  $s_i$ .

$$\text{Vol}_i(r; U) := \frac{\text{lp}}{k} + \sum_{(u,v) \in E[S_i(r; U)]} c(u, v) d_{uv} + \sum_{(u,v) \in \partial S_i(r; U)} c(u, v) \cdot (r - d_{s_i u}) \quad (\text{LP volume})$$

It’s best to think of this volume as the set  $S_i(r; U)$ ’s contribution to the LP objective. There are three parts above. The first,  $\text{lp}/k$  is an initialization which is kept for a technical reason that you will make sense soon. The second summation is the contribution to the LP objective due to edges complete present inside  $S_i(r; U)$ . The third is considering edges in  $\partial S_i(r; U)$  and sharing some of the LP contribution on these edges and attributing it to  $i$ . Note that for all such edges,  $r - d_{s_i u} \leq d_{s_i v} - d_{s_i u} \leq d_{uv}$  where the first inequality follows from the fact that  $v \in U \setminus S_i(r)$ , and the second is triangle inequality.

The following observation follows from the definition.

**Claim 2.** Fix any  $r \in (0, 0.5)$  and any  $i$  and any  $U \subseteq V$ . The set  $S_i(r; U)$  cannot contain  $s_j$  and  $t_j$  for any  $1 \leq j \leq k$ .

*Proof.* For any two vertices  $u, v \in S_i(r; U)$ , triangle inequality dictates  $d_{uv} \leq d_{u s_i} + d_{v s_i} \leq 2r < 1$ . Since  $d_{s_j t_j} \geq 1$ , they both can’t be in the same  $S_i(r; U)$ .  $\square$

This suggests the following algorithm. Figure out certain radii  $r_i$ ’s and peel out the “region of radius  $r$ ” around the terminal and delete. The boundaries of these “chunks” form a valid multicut.

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1: procedure REGION GROWING MULTICUT( $G = (V, E), c(e) \geq 0, \{s_i, t_i\}_{i=1, \dots, k}$ ):
2:   Solve (Multicut LP) to obtain  $x_e$ ’s and  $d_{uv}$ ’s.
3:    $U \leftarrow V; \mathcal{B} \leftarrow \emptyset; I \leftarrow \emptyset$ .  $\triangleright U$  is the set of alive vertices;  $\mathcal{B}$  is collection of balls.
4:   for  $1 \leq i \leq k$  do:
5:     If  $s_i \in S_j(r_j; U)$  for  $j < i$ , skip this for loop.
6:     Otherwise, find  $r_i \in [0, 0.5)$  which minimizes  $\frac{\sum_{e \in \partial S_i(r_i; U)} c(e)}{\text{Vol}_i(r_i; U)}$ .
7:      $\triangleright$  There are at most  $n$  different  $r$ ’s such that  $S_i(r; U)$  are distinct
8:      $U \leftarrow U \setminus S_i(r_i; U)$ 
9:     Add  $B_i := S_i(r_i; U)$  to  $\mathcal{B}$ .
10:  return  $F \leftarrow \bigcup_{B \in \mathcal{B}} \partial B$ .
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• *Analysis.*

**Theorem 2.** REGION GROWING MULTICUT returns a valid multicut  $F$  with cost  $\sum_{e \in F} c(e) \leq 4 \ln(k + 1) \text{lp}$ .

Observe, by definition, the sets  $B \in \mathcal{B}$  are disjoint sets. Furthermore, no  $B \in \mathcal{B}$  contains both  $s_j$  and  $t_j$  for any  $1 \leq j \leq k$ ; this follows from [Claim 2](#). Therefore,  $F$  is a valid multicut. Furthermore, each  $B \in \mathcal{B}$  is  $S_i(r_i; U_i)$  for some subset  $U_i \subseteq V$  which was the alive subset of vertices when this ball was being added. Let  $I \subseteq [k]$  be the  $i$ 's present in this enumeration; these are the  $s_i$ 's not ‘‘gobbled’’ by other  $S_j(r_j; U)$ 's.

**Claim 3.**  $\sum_{i \in I} \text{Vol}_i(r_i; U_i) \leq 2lp$ .

*Proof.* Note that the sum of the volumes is at most

$$lp + \sum_{(u,v) \in \cup_{i \in I} E[S_i(r_i; U_i)]} c(u,v)d_{uv} + \sum_{i \in I} \sum_{(u,v) \in \partial S_i(r_i; U_i)} c(u,v)d(u,v)$$

Now note that any edge  $(u,v) \in E$  appears in at most one  $E[S_i(r_i; U_i)]$  or  $\partial S_i(r_i; U_i)$ : it is the first  $i$  for which one of the end points enters  $S_i(r_i; U_i)$ . Therefore, the last two summations add up to at most  $\sum_{(u,v) \in E} c(u,v)d_{uv} \leq \sum_{e \in E} c_e x_e = lp$ .  $\square$

The heart of the analysis is in the following lemma.

**Lemma 1.** (Region growing lemma) Fix any subset  $U \subseteq V$  and any  $s_i \in U$ . There exists a  $r_i \in [0, 1/2)$  such that

$$\sum_{(u,v) \in \partial S_i(r; U)} c(u,v) \leq 2 \ln(k+1) \cdot \text{Vol}_i(r; U)$$

*Proof.* As defined, note that  $\text{Vol}_i(r; U)$  is a continuous, piece-wise linear function of  $r$ , and the crucial observation is that

$$\frac{d\text{Vol}_i(r; U)}{dr} = \sum_{(u,v) \in \partial S_i(r; U)} c(u,v)$$

This means that if  $\sum_{(u,v) \in \partial S_i(r; U)} c(u,v)$  is large, in particular larger than  $2 \ln(k+1) \text{Vol}_i(r; U)$ , then the rate of increase of the volume is rather large. On the other hand, even at  $r = 0.5$ , the volume can be at most the  $lp$ . And it began at  $lp/k$  (this is the technical reason to have this first term in the definition), and so the rate can't be large throughout, proving the lemma.

A little more formally, for the sake of contradiction, assume that the lemma's assertion is false. Then, we get the partial differential inequality

$$\forall r \in [0, 0.5), \quad \frac{d\text{Vol}_i(r; U)}{dr} > 2 \ln(2k) \cdot \text{Vol}_i(r; U) \Rightarrow \frac{d\text{Vol}_i(r; U)}{\text{Vol}_i(r; U)} > 2 \ln(k+1) \cdot dr$$

Therefore, if we integrate with  $r$  going from 0 to 0.5,

$$\int_{\text{Vol}_i(0)}^{\text{Vol}_i(0.5)} \frac{d\text{Vol}_i(r)}{\text{Vol}_i(r)} > 2 \ln(2k) \int_0^{1/2} dr$$

The LHS integrates to  $\ln\left(\frac{\text{Vol}_i(0.5; U)}{\text{Vol}_i(0; U)}\right)$ . By design,  $\text{Vol}_i(0; U) = lp/k$ . And,  $\text{Vol}_i(0.5) \leq lp(1 + \frac{1}{k})$ . Therefore, the LHS is at most  $\ln(k+1)$ . The RHS, however, integrates to  $\ln(k+1)$ , giving the desired contradiction.  $\square$

In the algorithm, we pick  $r_i$ 's which minimize the ration of  $c(\partial S_i(r_i; U))/\text{Vol}_i(r_i; U)$ , and so this ratio is at most  $2 \ln(2k)$ . Therefore, the cost of the edges deleted is at most

$$c(F) = \sum_{B \in \mathcal{B}} c(\partial B) = \sum_{i \in I} c(\partial S_i(r_i; U_i)) \leq 2 \ln(k+1) \cdot \sum_{i \in I} \text{Vol}_i(r_i; U_i) \underbrace{\leq}_{\text{Claim 3}} 4 \ln(k+1) |p$$

completing the proof of [Theorem 2](#).

## Notes

The region growing algorithm is from the paper [4] by Garg, Vazirani, and Yannakakis and was the first  $O(\log k)$ -approximation for the multicut problem. The technique of region growing itself is inspired by the seminal paper [5] by Leighton and Rao on the sparsest cut problem which we will discuss in a subsequent lecture. The randomized rounding algorithm is from the paper [2] by Calinescu, Karloff, and Rabani which followed their paper [1] on the multiway cut problem. On the other hand, it is possible there may not be any constant factor approximations for the multicut problem: the paper [3] by Chawla, Krauthgamer, Kumar, Rabani, and Sivakumar shows that it is UGC-hard to obtain any constant factor approximation.

## References

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